

# Local transformations of bipartite entanglement are rigid

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Joint work with Tony Metger and Henry Yuen

# Uhlmann transformations

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We call such a unitary  $U$  an Uhlmann transformation.

# Why care about Uhlmann transformations?

They appear in many fields:

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3. They characterize interesting complexity classes like the class of zero-knowledge provable unitaries, and the class of unitaries that can be implemented with the help of interaction with an all-powerful prover. [BEM+23]
4. Studying them will have interesting connections to math too! (Foreshadowing)

# The canonical Uhlmann transformation

In general, there could be many Uhlmann transformations for a pair of states (e.g., that differ off of the support of  $|C\rangle$ ). But there is a way to define a canonical isometry:

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It is known that two different Uhlmann transformations of the same pair of states must look the same on the support of  $W$ ! [BEM+23]

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Our answer: Yes, up to some parameters!

# Rigidity of Uhlmann transformations

Theorem: Let  $|C\rangle_{AB}, |D\rangle_{AB}$  be two quantum states with reduced on A  $\rho, \sigma$ . Then for all unitaries  $U$  such that

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There is a function  $\delta(\cdot)$  such that

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Here,  $\delta(\epsilon) = \left( \frac{2\kappa}{\eta} \right) \cdot \epsilon$ , depends on the following properties of the states  $|C\rangle, |D\rangle$ :

$$\kappa = \left\| \rho^{-1/2} \cdot \text{Image}(\rho^{1/2} \sigma \rho^{1/2}) \cdot \rho^{1/2} \right\|_{\text{op}}^2 \quad \text{and} \quad \eta = \lambda_{\min}(\rho^{-1} \# \sigma) .$$

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Matrix geometric mean:  $A \# B = A^{1/2} \cdot (A^{-1/2} B A^{-1/2})^{1/2} \cdot A^{1/2}$



# Proof Sketch

Let's think about the theorem statement as a maximization problem:

Maximize over  $U$ :  $\left\| \text{id} \otimes (W - U)W^*W | C \rangle \right\|^2$ .

Subject to:  $\langle D | \text{id} \otimes U | C \rangle = F(\rho, \sigma) - \epsilon$ ,

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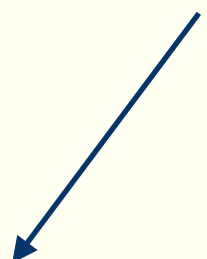
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# Proof Sketch

For our constraint, we can write it in a more standard form as:

$$\langle D | \text{id} \otimes U | C \rangle = \text{Tr} \left( \sqrt{\sigma} U \sqrt{\rho} \right) = \text{Tr} \left( U \sqrt{\rho} \sqrt{\sigma} \right)$$

$A = \sqrt{\sigma} \sqrt{\rho}$   


Since we want this to be a real number, we can write this constraint as:

$$\frac{1}{2} \left( \text{Tr} (UA^*) + \text{Tr}(U^*A) \right) .$$

# Proof Sketch

Let's think about the theorem statement as a maximization problem:

$$\text{Maximize over } U: \left\| \text{id} \otimes (W - U)W^*W | C \rangle \right\|^2.$$

$$\text{Subject to: } \frac{1}{2} \left( \text{Tr}(UA^*) + \text{Tr}(U^*A) \right) = F(\rho, \sigma) - \epsilon,$$

$$U^*U = \text{id}.$$

Very high level game plan: Use semi-definite programming duality to upper bound this!

# Proof Sketch

For the objective, we can expand it out as:

$$\begin{aligned} \left\| \text{id} \otimes (W - U)W^*W | C \rangle \right\|^2 &= \langle C | \text{id} \otimes W^*W | C \rangle \\ &\quad + \langle C | \text{id} \otimes (W^*WU^*UW^*W) | C \rangle \\ &\quad + 2\text{Re}\langle C | \text{id} \otimes (W^*WW^*UW^*W) | C \rangle \\ &\leq 2\text{Tr}(W^*W\rho) - \left( \text{Tr}(UW^*W\rho W^*) + \text{Tr}(W\rho W^*WU) \right) . \end{aligned}$$

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We will use the second term as the new objective function (since the first term does not depend on U).

# Proof Sketch

Let's think about the theorem statement as a maximization problem:

Maximize over  $U$ :  $-\left(\text{Tr}(UW^*W\rho W^*) + \text{Tr}(W\rho W^*WU)\right)$  .

Subject to:  $\frac{1}{2} \left(\text{Tr}(UA^*) + \text{Tr}(U^*A)\right) = F(\rho, \sigma) - \epsilon$  ,

$$\begin{pmatrix} \text{id} & U \\ U^* & \text{id} \end{pmatrix} \geq 0 .$$

Now, this can be transformed into a standard form semidefinite program.

# Proof Sketch

The dual of the SDP is:

Minimize over  $Y_1, Y_2, \alpha$ :  $\text{Tr}(Y_1) + \text{Tr}(Y_2) + \alpha (F(\rho, \sigma) - \epsilon)$

Subject to:  $\begin{pmatrix} Y_1 & \frac{1}{2}\alpha A \\ \frac{1}{2}\alpha A^* & Y_2 \end{pmatrix} \geq \frac{1}{2} \begin{pmatrix} & -W\rho W^*W \\ -W^*W\rho W & \end{pmatrix}$

$Y = \begin{pmatrix} Y_1 & & \\ & Y_2 & \\ & & \alpha \end{pmatrix}$  Hermitian

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If we find any feasible solution to this, we get an upper bound on the rigidity.

# Proof Sketch

We are going to identify a nice matrix/choice of  $\alpha$  to plug in. Define the following:

$$\alpha = -\kappa/\eta$$

$$T = \frac{1}{2} (\alpha A^* + P\rho W^*)$$

Then we plug in the following for  $Y_1$ ,  $Y_2$  and we get the answer we want.

$$Y_1 = \sqrt{T^*T}$$

$$Y_2 = T \left( \sqrt{T^*T} \right)^{-1} T^*$$

# Dependence on parameters $\kappa, \eta$

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Theorem: For every  $\eta$ , there is a pair of states whose matrix geometric mean has smallest eigenvalue  $\eta$ , and there is a transformation that saturates the bound, i.e.

$$\|\text{id} \otimes (W - U)W^*W | C\rangle\|^2 \geq 2\epsilon/\eta$$

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$$\|\text{id} \otimes (W - U)W^*W | C\rangle\|^2 \geq 2\epsilon/\eta$$

Theorem: For every  $\kappa \geq 1$  and all  $\epsilon$ , there is a pair of states with  $\eta \geq 1$  and  $\kappa = \left\| \rho^{-1/2} \cdot \text{Image}(\rho^{1/2} \sigma \rho^{1/2}) \cdot \rho^{1/2} \right\|_{\text{op}}^2$  such that

$$\|\text{id} \otimes (W - U)W^*W | C\rangle\|^2 \geq \kappa \epsilon^2$$

# Uhlmann transformations for math

Our rigidity theorem seems to be a very general form of rigidity, it implies other well known stability theorems. Let's consider one such example!

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A representation of a group is a mapping from a group  $G$  to unitaries on some vector space. The representation satisfies  $U_g U_h = U_{gh}$ .

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A representation of a group is a mapping from a group  $G$  to unitaries on some vector space. The representation satisfies  $U_g U_h = U_{gh}$ .

An approximate representation is a collection of unitaries such that

$$\frac{1}{d} \mathbb{E}_{g,h} \left[ \|U_g U_h - U_{gh}\|_1^2 \right] \leq \epsilon$$

# Uhlmann transformations for math

Given an  $\epsilon$ -approximate representation, how close is it to a real representation? Let's consider the following pair of states:

$$|C\rangle = \frac{1}{|G|} \sum_{g,h \in G} \left( \text{id} \otimes U_g \right) | \text{EPR} \rangle_{AB_1} |g\rangle_{B_2} |h\rangle_{B_3},$$

$$|D\rangle = \frac{1}{|G|} \sum_{g,h \in G} \left( \text{id} \otimes U_{hg} \right) | \text{EPR} \rangle_{AB_1} |g\rangle_{B_2} |h\rangle_{B_3}.$$

Let's consider the Uhlmann transformations that act on the B register.

# Uhlmann transformations for math

$$|C\rangle = \frac{1}{|G|} \sum_{g,h \in G} \left( \text{id} \otimes U_g \right) |\text{EPR}\rangle |g\rangle |h\rangle ,$$

$$|D\rangle = \frac{1}{|G|} \sum_{g,h \in G} \left( \text{id} \otimes U_{hg} \right) |\text{EPR}\rangle |g\rangle |h\rangle .$$

The canonical Uhlmann transformation is:

$$W = \sum_{g,h} \left( U_{hg} U_g^* \right)_{B_1} \otimes |g,h\rangle\langle g,h|_{B_2 B_3} .$$

An approximate one is:

$$U = \sum_h \left( U_h \right)_{B_1} \otimes |h\rangle\langle h|_{B_3} .$$

# Uhlmann transformations for math

Applying the rigidity theorem to these two unitaries:

$$W = \sum_{g,h} \left( U_{hg} U_g^* \right)_{B_1} \otimes |g, h\rangle\langle g, h|_{B_2 B_3}, \quad \text{and} \quad U = \sum_h \left( U_h \right)_{B_1} \otimes |h\rangle\langle h|_{B_3}$$

Gives us the following: There exists an isometry  $V$  and exact representation  $R$

$$\frac{1}{d} \mathbb{E}_g \left[ \|U_g - V^* R(g) V\|_1^2 \right] \leq \epsilon$$

# Next steps?

We proved a rigidity theorem for Uhlmann transformations, but open questions still remain.

1. Can we relate other notions of stability to Uhlmann transformations? For example, is CHSH rigidity a consequence of the rigidity of the Uhlmann transformation for some pair of states? What about general algebra's and non-local games?
2. There is a way to round states to nearby states so that  $\eta$  (the minimum eigenvalue of the matrix geometric mean) is well behaved, does the same exist for  $\kappa$ ?

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Thanks for listening!